

# FLOW OF PURELY VISCOUS NON-NEWTONIAN FLUIDS IN STRAIGHT NON-CIRCULAR DUCTS: A REVIEW AND COMPARISON OF PROCEDURES FOR RAPID ENGINEERING FRICTION FACTOR ESTIMATES

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## ABSTRACT

This paper presents a review and comparison of approximate methods for rapid estimates of the friction factor for stabilized flow of purely viscous fluids in non-circular ducts. Results of the approximate procedures, for the particular case of a power-law fluid, are compared with data obtained by numerical integration. For cross-sectional geometries formed by singly connected regions without sharp corners, all available approximate procedures yield results with relative deviations from the numerical data not exceeding about 5%. However, for cross sections formed by doubly connected regions such as for flow in the gap between a square duct with an inner centered cylindrical core, or for an eccentric annulus, deviations may exceed much more than 15% and neither of the existing methods can be recommended.

KEYWORDS: FLOW IN DUCTS, POWER-LAW FLUIDS, NON-CIRCULAR CROSS SECTIONS, FRICTION FACTOR

## INTRODUCTION

For laminar flow of Newtonian fluids in ducts, theoretical as well as numerical results for the friction factor are most frequently expressed in term of the Poiseuille dimensionless group

$$Po = f Re, \quad (1)$$

where the Fanning friction factor  $f$  and Reynolds number are defined as,

$$f = \frac{D_e \Delta p}{2 \rho \bar{u}^2 L}, \quad Re = \frac{\bar{u} D_e \rho}{\mu}, \quad (2,3)$$

where  $D_e = 4A/O$  is the equivalent diameter,  $\bar{u}$  denotes the volumetric mean velocity,  $\Delta p$  stands for the pressure difference on the duct length  $L$  and  $\rho$ ,  $\mu$  denote the fluid density and dynamic viscosity.

For Newtonian fluids, the  $f Re$  product in Eq. (1) depends upon the particular form of the cross-sectional geometry only, e.g. its value is 16 for a circular tube. For power-law fluids for which the rheological model  $\tau = k \dot{\gamma}^n$  holds, a generalized Reynolds number  $Re_B$  is defined,

$$Re_B = \frac{\bar{u}^{2-n} D_e^n \rho}{2^{3(n-1)} k}, \quad (4)$$

for which,

$$f Re_B = f Re_B(n, \text{cross-sectional geometry}). \quad (5)$$

## APPROXIMATE METHODS FOR CALCULATING THE FRICTION FACTOR

Kozicki, Chou and Tiu, [1] appear to be the first who proposed to estimate the friction factor from the equation

$$f Re_B = 16 \left[ \frac{a + bn}{n} \right]^n, \quad (6)$$

where  $a$ , and  $b$  are geometrical parameters which are determined from the corresponding solution for Newtonian flow in the same cross-sectional geometry, see. e.g. [1] or [2].

Miller, [3], proposed in 1972 the following approximation,

$$f Re_B = 16 \left[ (a + b) \frac{3n + 1}{4n} \right]^n. \quad (7)$$

Since, according to Kozicki et al, [1],

$$a + b = f Re / 16, \quad (8)$$

Miller's method employs only one parameter, more or less easily obtainable from the corresponding Newtonian solution.

In 1995, analyzing values of Kozicki's geometrical parameters, Delplace and Leuliet [4], deduced the following correlation between the parameters,

$$\frac{b}{a} = \frac{3}{a + b}. \quad (9)$$

Substituting from Eq. (9) into Kozicki's Eq. (6) yields Delplace and Leuliet's approximation,

$$f Re_B = 16 \left[ (a + b) \frac{3n + a + b}{(3 + a + b)n} \right]^n, \quad (10)$$

which again employs only one parameter, namely that in Eq. (8).

Recently, Liu and Masliyah [5], developed a three-shape-factor method embodied in the relation

$$f Re_B = 16 \left( k_1 / 2 \right)^n \left( 1 + \frac{1-n}{k_2 n} \right)^n k_3^{n-1}, \quad (11)$$

similar to that developed by Kozicki et al, [1]. Since it is not difficult to show that the shape factors  $k_1$  and  $k_2$  are related to the  $a$  and  $b$  parameters by

$$k_1 = 2(a + b), \quad k_2 = \frac{b}{a} + 1, \quad (12,13)$$

and taking in account that Liu and Masliyah adopted Delplace and Leuliet's assumption in Eq. (9), Eq. (11) is transformed into,

$$f Re_B = 16 \left[ (a + b) \frac{3n + a + b}{(3 + a + b)n} \right]^n k_3^{n-1}, \quad (14)$$

which is very similar to Delplace and Leuliet's result in Eq. (10). In order to apply all the methods outlined so far, a Newtonian flow solution in the particular cross-sectional geometry is sufficient. A certain drawback of the method

in Eq. (14) originates from the fact that the determination of the  $k_3$  shape-factor requires a numerical solution for  $n$  different from unity.

#### A COMPARISON OF THE APPROXIMATE METHODS

##### Cross section formed by a singly connected region

In order to check the accuracy of all the four approximate methods for a cross-sectional geometry formed by a singly connected region, a symmetrical L-profile was used, see Figure. 1. Results obtained by a finite difference numerical technique, [6], were taken as reference “exact” values. For the particular case of  $B/A = 0.5$ , excellent agreement was found with values of  $f Re_B$  reported by Ta-Jo Liu, [7], from  $n=1$  down to  $n=0.5$ .

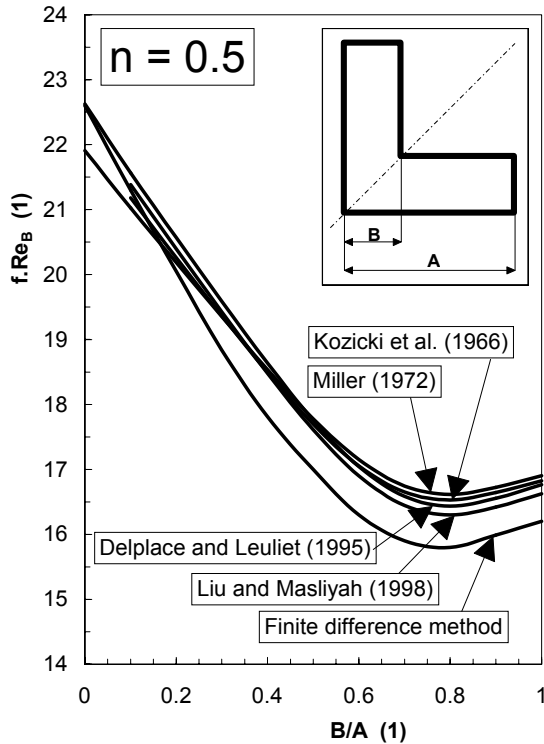


Figure 1. A comparison of the approximate methods for a symmetrical L-profile.

In Figure 2. the relative deviation  $\omega$ ,

$$\omega = \frac{(f Re_B)_{approx} - (f Re_B)_{numerical}}{(f Re_B)_{numerical}}, \quad (15)$$

is plotted against the  $B/A$  simplex. As expected, Liu and Masliyah's procedure yield the best results due to the fact that the  $k_2$  and  $k_3$  shape-factors were extracted from a numerical solution [7]. Kozicki et al. and Delplace and Leuliet's methods exhibit similar results, the latter being more advantageous due to the fact that it employs a single shape-factor only. Generally, all four methods predict correctly a minimum of  $f Re_B$  values near  $B/A \doteq 0.75$ , relative deviation of all methods remains below 5%.

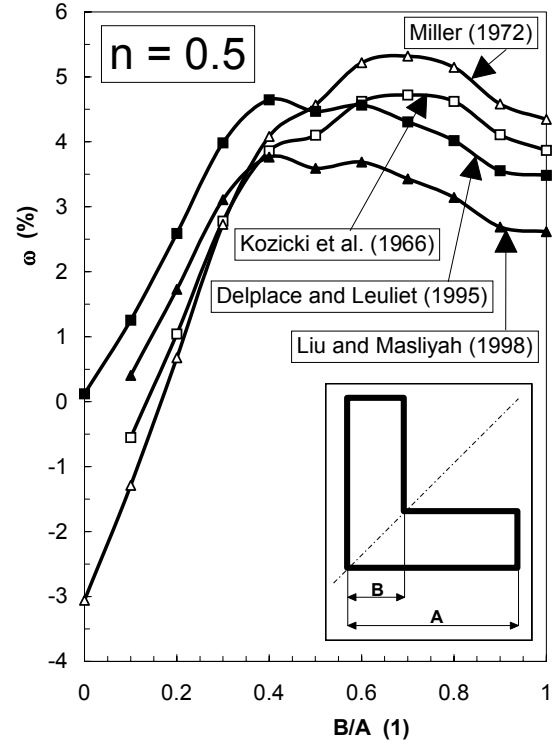


Figure 2. Relative error of approximate methods for a symmetrical L-profile.

##### Cross section formed by a multiply connected region

As an example of a cross section formed by a doubly connected region, the eccentric annulus geometry in Figure 3 was chosen. The shape factors  $a$  and  $b$  were determined from the Newtonian solution published by Piercy, Hooper and Winny [8]. Geometry of the cross section is defined by the gap curvature  $\kappa = 2r/2R = d/D$  and by the dimensionless eccentricity  $e^* = e/(R-r)$ . Results of the approximate analyses were compared with numerical data reported by Guckes in 1975, [9], for  $n=0.5$ . From Figure 3. and 4. it is clear that, for  $e^* < 0.5$  the relative error of all three methods remains below 5%, Kozicki's method resulting perhaps in slightly more accurate values. Since  $k_3$  values could not be obtained from the graphically presented data in reference [9], in view of the conclusions in the original work [5], the obvious choice is to set  $k_3 \doteq 1$ . If this is done, Liu and Masliyah's predictions coincides with Deplace's method, [4]. However, for values of  $e^* > 0.5$ , accuracy of all the approximations decreases rapidly and, with  $e^*$  approaching unity (i.e. for the inner core or tube touching the outer tube) makes all the approximate methods useless. A similar phenomenon has been reported for the doubly connected cross section between a circular core enclosed in a square duct, [10].

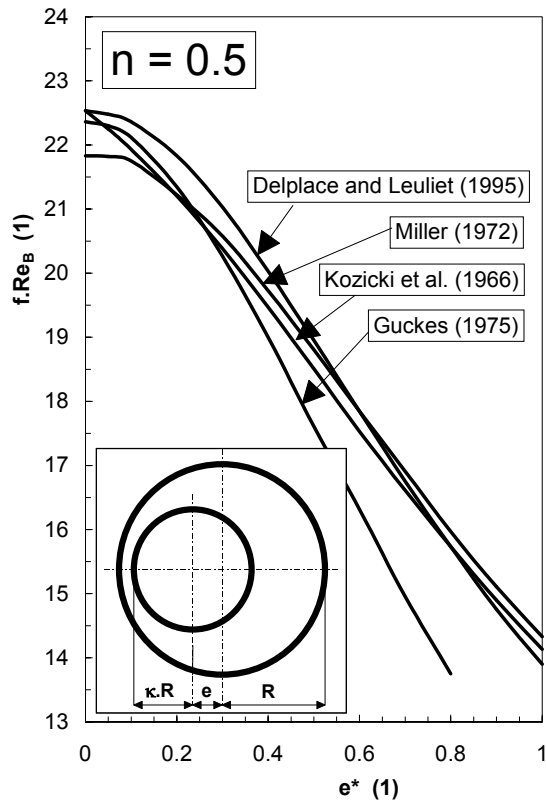


Figure 3. A comparison of approximate methods for an eccentric annulus.

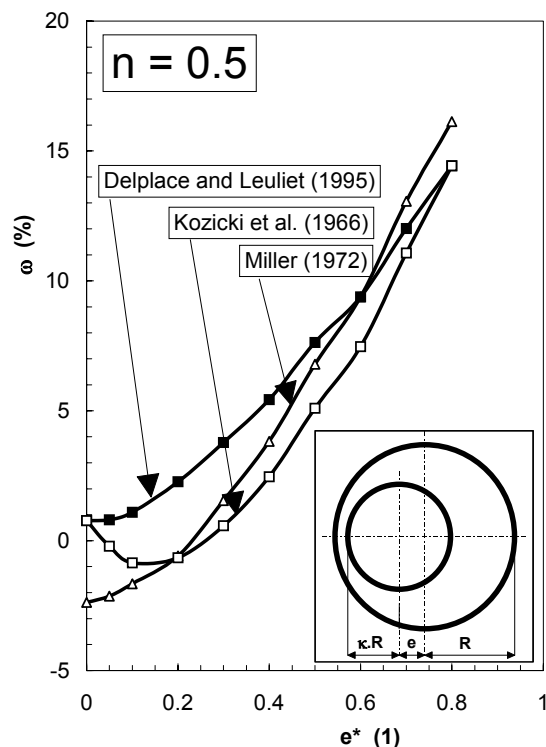


Figure 4. Relative error of approximate methods for an eccentric annulus.

## CONCLUDING REMARKS

For cross sections formed by singly connected regions and values of  $f Re/16$  differing not much from unity, all four approximate procedures yield useful results with errors usually below 5%, mostly in the whole range of  $0 < n < 1$ . From the point of view of computational effort, Deplace and Leuliet's method may be recommended giving results with acceptable accuracy and just a single shape factor in Eq. (8). For cross sections formed by multiply connected regions, especially those exhibiting very sharp corners (such as in the gap of the annular geometry for  $e^* \rightarrow 1$ ), neither of the methods available so far can be recommended and further work is needed.

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